# Simulating **Euclid S**pectroscopic Telescope bservations

INAF

with Dida Markovic, Sylvain de la Torre and the galaxy clustering end-to-end group

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> Paving the way... Sesto, 5 July 2018

### Euclid survey instruments

- Near-IR spectrograph (NISP)
  - Pixel scale 0.3 arcsec/pixel Ο
  - Slitless spectrograph Ο
  - Grism dispersion 13.4 A/pixel Ο
- Visible imager (VIS), not presented here



Grism wheel



Red 0,90,180 Blue 0



### A panchromatic view



\*NISP sim does not include cosmic rays.





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## Spectroscopic surveys

### • Wide

- ~ 15 000 sq deg
- Imaging magnitude limit: H ~ 24
- Emission line flux limit: ~ 2 x  $10^{-16}$  erg/s/cm<sup>2</sup>
- 4 passes
- 3 red grism orientations

### • Deep

- ~ **40 sq deg**
- H ~ 26
- $\circ$  Flux ~ 0.2 x 10<sup>-16</sup> erg/s/cm<sup>2</sup>
- >> 4 passes
- Red and blue grisms





## **Data systematics**

- Foregrounds
  - o Zodi
  - Straylight
  - Extinction
- Contamination
  - Spectra overlaps
  - Cosmic rays
  - Persistence
- Redshift measurement
  - Systematic misidentification
  - Spurious detection rate
  - Random error
  - Template bias

- Calibration error
  - Spectrophotometry
  - Wavelengths





# Simulation tools

- Pixel simulations
  - IModel (Garilli et al)
  - TIPS (Zoubian et al)
- Catalog level (bypasses)
  - Pypelid (Granett, Markovic et al)

★ We are developing pypelid to scale up to simulations the size of the Euclid wide survey



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## Inputs

- Flagship galaxy properties
  - $\circ$  RA, Dec, z
  - o mag J, H
  - Flux Ha, Hb, NII, SII, OIII, OII
    - Bulge, disk: scale, fraction, axis ratio
      - Foregrounds
        - Stars
          - o Zodi
          - Out-field straylight
        - Milky way extinction



# Signal and noise





### Signal and noise

- Emission line signal  $S = A_{surf} t_{exp} q \int T(\lambda) f_{\lambda}(\lambda) \ 10^{-0.4A(\lambda)} \frac{\lambda}{hc} d\lambda$
- Noise

$$\sigma^2 = t_{exp} n_{dark} + \sigma^2_{read} + \sum_i \sigma^2_{diffuse,i}$$

### **Detection significance**

- Simulate noisy emission line spectrum
  - Point-spread function
  - Disk & bulge size
  - Line broadening
  - No continuum
- Do a template fit on the 1D spectrum
- Template-fit amplitude defines SNR:

$$a = \frac{\sum d\sigma^{-2}t}{\sum t\sigma^{-2}t}$$





### Spurious sources - false detection rate

- The SNR cut will set the false-detection rate
- We can model the distribution by running noise-only spectra
- Model the SNR null distribution:
  - At fixed redshift: Chi2 with one deg of freedom, or
  - Varying redshift: Gumbel distribution



### Galaxies Randoms 8x Systematics: tiling pattern -20.0-20.2Dec -20.4-20.6 -20.8-21.08.0 8.8 8.2 9.0 8.6 8.4 RA

Galaxies

### Randoms 8x

# Systematics: tiling pattern-

# Systematics: tiling pattern

Uniform randoms (not expected to work)



Lines of the same color show different shuffling realizations (shot noise)

### Systematics: contamination

- Overlapping spectra contribute to the noise
- Is this an important exclusion effect like SDSS fiber collisions or VIMOS slit constraints?





### Systematics: contamination

$$SNR = \frac{S}{\sqrt{S + C + N_{sky}}}$$

- We are in the  $N_{sky} > C$  regime
  The exception is bright galaxies at low
- The exception is bright galaxies at low redshift



### **Contamination model**

### [Based on PROFESS by S. de la Torre]



# **Run configurations**

- Flagship 1.5.2
- Selection: H < 24
- 307 pointings ~ 175 sqr deg
- Foregrounds:
  - o Zodi
  - Out-field stray light
  - Milky Way extinction
- Pypelid run with contamination on and off
- Detection threshold 5 sigma



### **Contamination tests: completeness**



### Contamination tests: correlation function



### **Discussion points - contamination**

- Continuum contamination will come from foreground bright galaxies (stars) H<20</li>
- Uncorrelated with target sample 0.9<z<1.8
- What about contamination with line features?
  - This could come from sources at any redshift
  - Depends on OU-SIR decontamination algorithm
  - Insufficient orientations could leave residual contamination features in stacked spectra.



### Systematics - redshift measurement error

- Pypelid models the extraction process and runs a template fitter to get a redshift measurement with error
- Includes
  - Spurious line detection
  - Line misidentification
  - Estimation of significance
  - Estimation of the false detection rate by running noise-only spectra
- Not implemented (yet)
  - Redshift priors (eg magnitude, color or size)
  - Wavelength calibration error model

## Line misidentification

- Contamination rates estimated from Flagship populations
- Ultimately to be calibrated from the Deep survey



### Line misidentification





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### Random redshift error - RSD



### Discussion points - redshift error

- Line misidentification rates will depend strongly on the priors
  - Magnitude, color, size, ...
  - Line misidentification can be put into the model
- Best fit parameters can change with redshift error, even though we know how to model it perfectly...
  - Information is lost
  - Watch for degeneracies between redshift error and other RSD model parameters
- Correlations between redshift error, galaxy type and environment can be troublesome
  - But we have not seen a strong effect in Flagship

# Pypelid performance

- Exposures processed in parallel with MPI
  - There are remaining efficiency issues
- ~100 core-days/survey





## SESTO summary

- Current pixel-level simulations are limited to a few pointings
- We are developing algorithms to bypass pixels and model survey systematics at the catalog level
- pypelid is our fast and modular survey simulator
- With the Flagship mock we've started looking at systematics for Euclid Wide clustering analyses
  - Tiling pattern and visibility mask
  - Contamination by continuum sources
  - Random and systematic redshift error

# More paving to come!